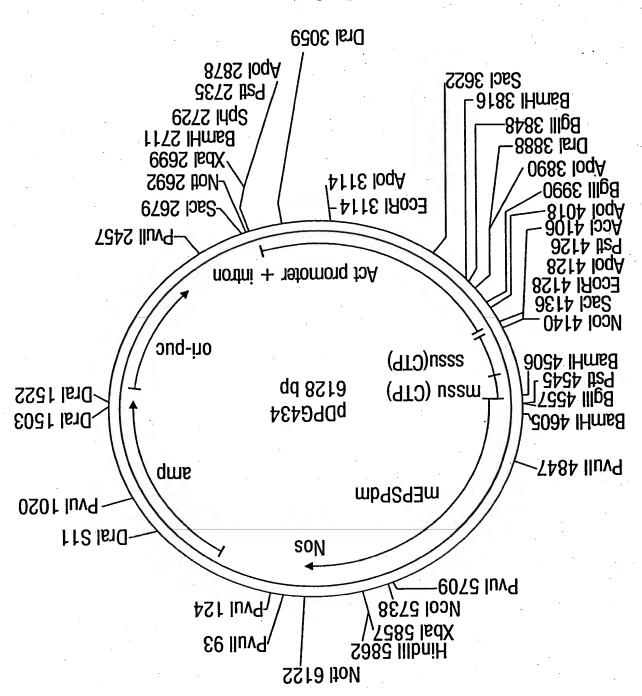


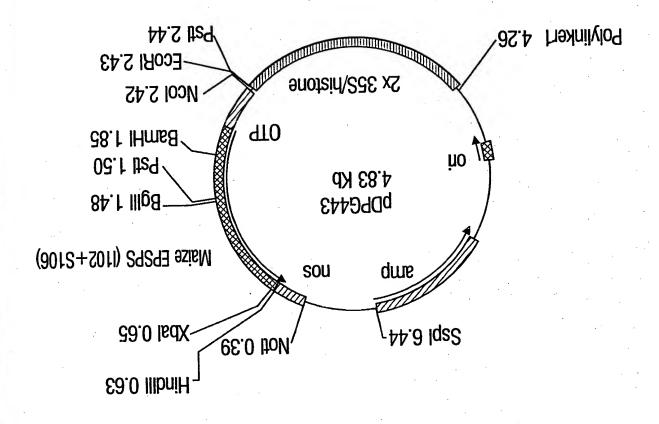
FIG. 2





HG.3





Polylinker1: 4.26/Sacl.BstXl.Sacll.Xmalll.Notf.Xbal.Spel.BamHl.

FIG. 4

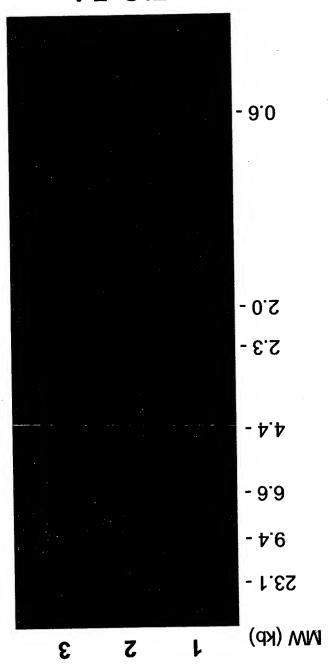
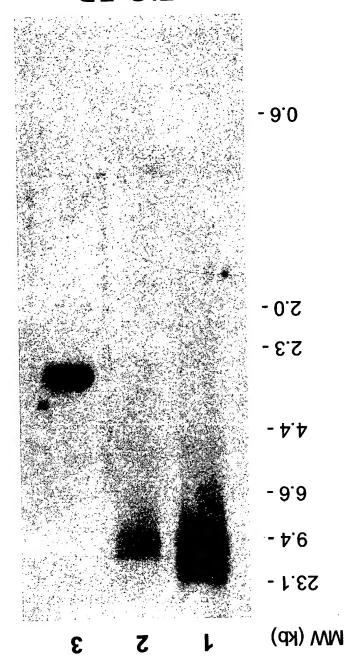


FIG.5A

FIG.5B



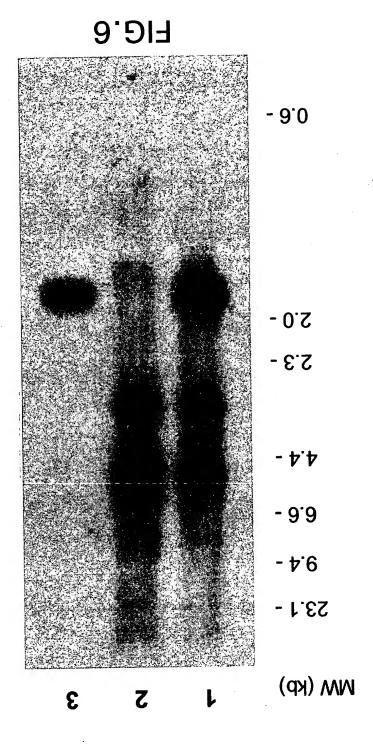
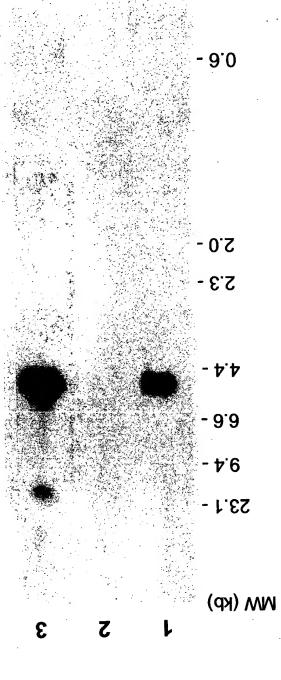
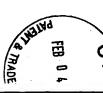




FIG.7







			MEAN E	MEAN ELH 10 DAT V4 ROUNDUP APP	V4 ROUND		ICATION		MALE
HYBRID	EVENT	0X	1X	Diff	RANK	4X	Diff	RANK	STERILE
DK580	GA21	104.1	102.4	1.7	1	102.3	1.8	} -	None
	FI117	100.1	97.7	2.3	2	97.7	2.4	2	None
	6J11	105.0	102.4	2.6	3	98.6	6.5	3	None
	GG25	105.5	99.4	6.2	4	97.3	8.3	4	None
DK626	GA21	98.8	97.1	1.8	3	97.9	1.0	L	None
	FI117	96.4	91.3	5.1	4	92.7	3.7	ယ	None
	GJ11	96.0	96.8	-0.8	⊢ ⊸1	94.0	2.0	2	None
	GG25	99.5	97.8	1.6	2	93.1	6.4	4	None

FIG. 8A



			MEAN E	MEAN ELH 10 DAT V8 ROUNDUP APP	V8 ROUND		ICATION		MALE
HYBRID	EVENT	8	¥	Diff	RANK	4X	Diff	RANK	STERILE
DK580 ·	GA21	142.7	139.6	3.1	ယ	139.2	3.5	2	None
	FI117	143.4	139.5	3.9	4	139.1	4.3	ω	None
	6625	141.4	139.8	1.6	2	136.5	5.0	4	Yes
- · · · ·	6.11.1	139.3	139.3	0.0	1	137.3	2.0	⊢ ⊸	Yes
DK826	GA271	134.8	139.2	-4.4	1	134.0	0.8	۳	None
() ()	F1117	135.4	134.2	1.3	4	132.1	3.3	4	None
	6.111	135.7	137.7	-2.0	2	133.1	2.6	3	Yes
	GG25	135.5	136.6	-1.0	3	134.0	1.6	2	Yes

FIG. 8B

JH3	Mq	
Allo		
7	끏	C
AAC		-
12		-

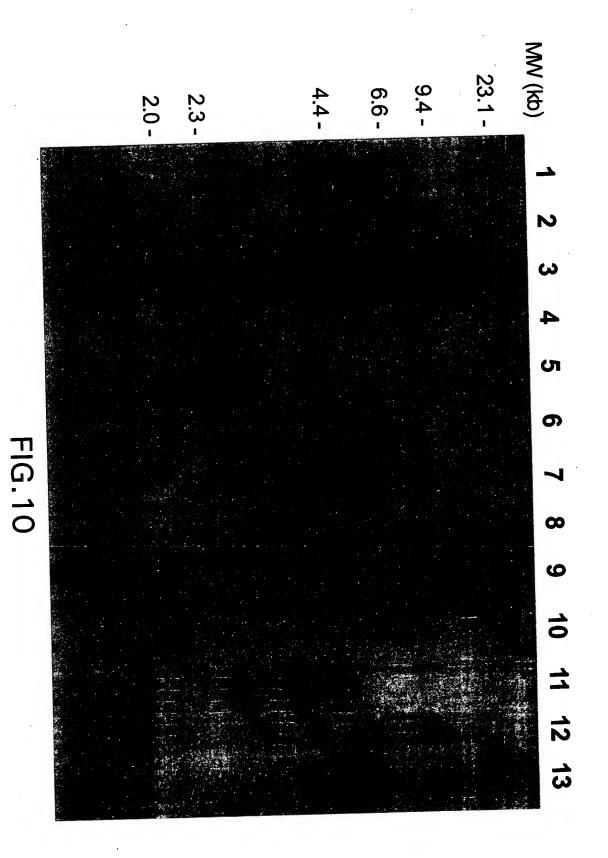
LEVEL 1	L 1	LEVE	EVEL 2	DIFFFRENCE	
HYBRID	RU*@	HYBRID	RU*@TIMING	(LEV. 1 - FV 2)	ProbyT
	TIMING				000
DK580	0X	DK580 FI117	0X	-16.60	0 0330
DK580	X0	DK580 FI117	4X@V4	11 33	0.000
DK580 FI117	0X	DK580 FI117	4X@V4	27 97	0 0000
DK580	0X	DK580 GA21	0X	3 67	0.6378
DK580	0X	DK580 GA21	4X@V4	-5.35	0.0070
DK580 GA21	0X	DK580 GG21	4X@V4	-9 02	0.1320
DK580	0X	DK580 GG25	0X	-4 13	0.67
DK580 :	0X	DK580 GG25	4X@V4	-3 50	0.6531
DK580 GG25	0X	DK580 GG25	4X@V4	0.63	0.0352
DK580	0X	DK580 GJ11	0X	-9 43	0.3052
DK580	0X	DK580 GJ11	4X@V4	-6 05	0.276
DK580 GJ11	0X	DK580 GJ11	4X@V4		0.6640
		i			

FIG.9A



	HYBRID		DK626	DK626	DK626 FI117	DK626	2	DK 626	2	灵;		JK626	DK626 GG25	DK 626
I EVEI	RID		526	526	FI117	526	DK626	DK626 GA21	DK 626	DK 626	GG25	DK 626		DK626
	RU*@	TIMING	0X	0X	0X	0X	0X	0X	X0	0X	0X	0X	0X	
LEVEL 2	HYBRID		DK626 FI117	DK626 FI117	DK626 FI117	DK626 GA21	DK626 GA21	DK626 GG21	DK626 GG25	DK626 GG25	DK626 GG25	DK626 GJ11	DK626 GJ11	
1 2	RU*@TIMING		0X	4X@V8	4X@V8	0X	4X@V8	4X@V8	0X	4X@V8	4X@V8	0X	4X@V8	
DIFFERENCE	(LEV. 1 - LEV.2)		-11.10	5.12	16.20	-2.58	-9.63	-7.05	-6.93	23.97	30.90	1.70	27.62	
	Prob>T		0.1559	0.5113	0.0388	0.7401	0.2171	0.3658	0.3738	0.0024	0.0001	0.8272	0.0005	0 0011

FIG.9B



A TABILA

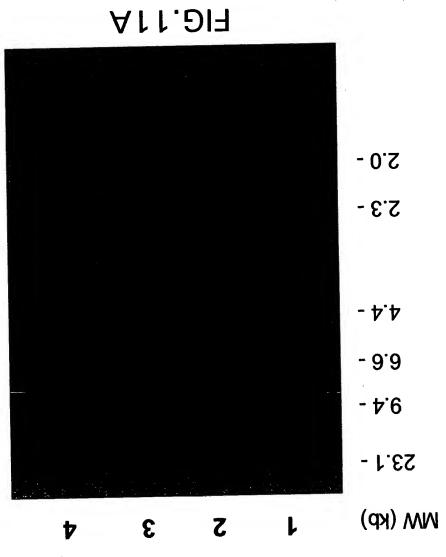
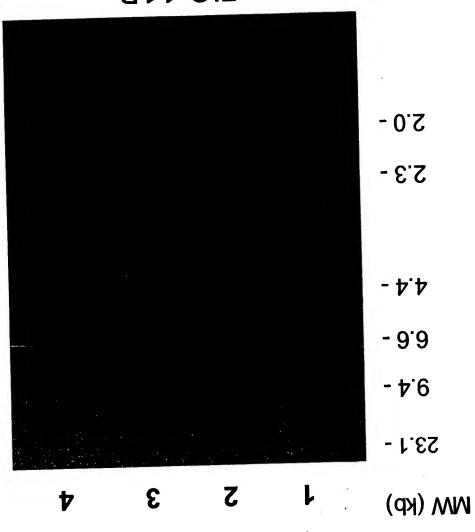
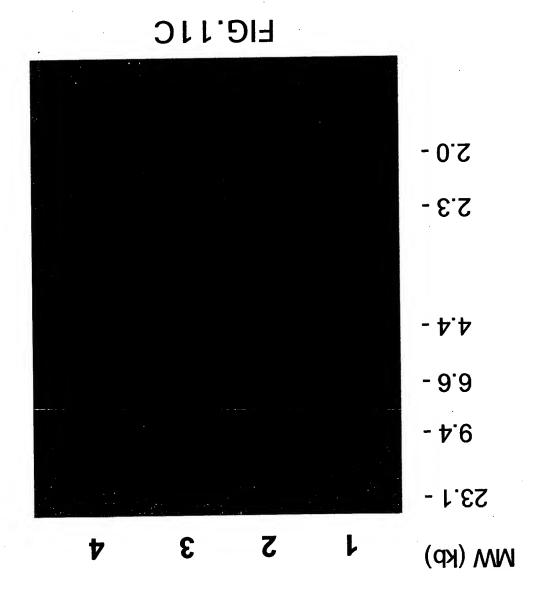


FIG.11B



MA



551 401 351 301 251 VPRMRERPIG DLVVGLKQLG ADVDCFLGTD CPPVRVNGIG 451 NMNKMPDVAM TLAVVALFAD GPTAIRDVAS WRVKETERMV AIRTELTKLG 201 AVVVGCGGKF PVEDAKEEVQ LFLGNAGIAM RSLTAAVTAA GGNATYVLDG 151 SLSNRILLIA 101 TASLPVARRS SRSLGNVSNG GCTRKTFPDY FDVLSTFVKN GSISSQYLSA LLMAAPLALG DVEIEIIDKL ISIPYVEMTL RLMERFGVKA CGTTSLQGDV KFAEVLEMMG AKVTWTETSV TVTGPPREPF EHSDSWDRFY IKGGQKYKSP KNAYVEGDAS SASYFLAGAA ASVEEGPDYC IITPPEKLNV TAIDTYDDHR MAMAFSLAAC AEVPVTIRDP GGRVQCMQVW PAYGNKKFET LSYLPPLSMA PTVMMASSAT AVAPFQGLKS MASISSSVAT VSRTAPAQAN MVAPFTGLKS NAAFPTTKKA NDFSTLPSNG ALSEGTTVVD NLLNSEDVHY MLGALRTLGL SVEADKAAKR GRIRCMAGAE EIVLQPIKEI SGTVKLPGSK GRKHLKAIDV GLPGGKVKLS ITGGTVTVEG

FIG. 12

FIG. 13-3	FIG. 13-1
FIG. 13-4	FIG. 13-2

FIG. 13

ATHERISO O

963019 Test Map Example

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S	2	2	2	2	2	N	2	2	2	2	2	ယ	ယ	ယ	ω	ω	ယ	ယ	ယ	ယ	ယ	ယ	ω	REP	
	-		2	2	2	ယ	ယ	ယ	4	4	4	<u>г</u>	<u> </u>	⊢ ¹	2	2	2	ယ	ယ	သ	4	4	4	ROW	
T-4xeV8	FI117	DK580	T-1X@V8	GG25	DK580	T-4X@V8	GG21	DK580	T-0X	GJ11	DK580	N-0X		DK580	T-1X@V8	GG25	DK580	T-1X@V4	FI117	DK580	T-4X@V4	GA21	DK580	COL1	
N-0X		DK580	N-OX		DK580	T-1X@V8	GA21	DK580	T-1X@V4	GJ11	DK580	T-4X@V8	GJ11	DK580	T-4X@V8	GG25	DK580	T-1X@V8	FI117	DK580	T-4X@V8	GA21	DK580	COL2	
T-0X	FI117	DK580	T-4X@V4	GG25	DK580	T-4X@V4	GA21	DK580	N-0X		DK580	T-1X@V4	GJ11	DK580	T-0X	GG25	DK580	N-OX		DK580	T-1X@V8	GA21	DK580	COL3	
T-1X@V4	FI117	DK580	T-1X@V4	GG25	DK580	T-0X	GA21	DK580	T-4X@V4	GJ11	DK580	T-4X@V4	GJ11	DK580	T-1X@V4	GG25	DK580	T-0X	FI117	DK580	T-1X@V4	GA21	DK580	COL4	
T-1X@V8	FI117	DK580	T-0X	GG25	DK580	N-OX		DK580	T-1X@V8	6J11	DK580	T-0X	GJ11	DK626	N-0X		DK580	T-4X@V4	FI117	DK580	N-0X		DK580	COL5	
T-4X@V4.	FI117	DK580	T-4X@V8	GG25	DK580	T-1X@V4	GA21	DK580	T-4X@V8	GJ11	DK580	T-1X@V8	GJ11	DK626	T-4X@V4	GG25	DK580	T-4X@V8	FI117	DK580	T-0X	GA21	DK580	COL6	
T-4X@V4	GA21	DK626	T-4X@V4	FI117	DK626	N-0X		DK626	T-1X@V8	GJ11	DK626	T-4X@V8	FI117	DK626	T-1X@V4	GG25	DK626	T-1X@V8	GA21	DK626	T-4X@V4	GJ11	DK626	COL7	
N-0X	,	DK626	T-0X	FI117	DK626	T-0X	GG25	DK626	T-1X@V4	GJ11	DK626	T-0X	FI117	DK626	T-4X@V8	GG25	DK626	T-4X@V4	GA21	DK626	T-1X@V8	GJ11	DK626	COL8	
J						1			1									,	-		,				•

FIG. 13-1

 T-4X@V8	DK626	T-1X@V4	FI117	DK626	T-4X@V8	GG25	DK626	T-4X@V8	GJ11	DK626	T-1X@V8	FI117	DK626	T-0X	GG25	DK626	N-0X		DK626	N-OX		DK626	COL9
T-1X@V8	DK626	T-4X@V8	FI117	DK626	T-1X@V8	GG25	DK626	T-4X@V4	GJ11	DK626	T-4X@V4	FI117	DK626	T-1X@V8	GG25	DK626	T-0X	GA21	DK626	T-4X@V8	GJ11	DK626	COL10
T-0X	DK626	T-1X@V8	F1117	DK626	T-1X@V4	GG25	DK626	N-OX		DK626	N-OX		DK626	T-4X@V4	GG25	DK626	T-1X@V4	GA21	DK626	T-0X	GJ11	DK626	COL11
T-1X@V4	GA21	N-0X		DK626	T-4X@V4	GG25	DK626	T-0X	GJ11	DK626	T-1X@V4	FI117	DK626	N-OX		DK626	T-4X@V8	GA21	DK626	T-1X@V4	GJ11	DK626	C0L12
 	•	٠	•														_						

FIG. 13-2

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N-OX		UKSBU	מארסס	T-4X0V8	GJ11		UKZNU	1-4X@V4	TAVOVA	F111/	07000	DKS80	1-4X640	H AVOVO	GA21	DOCAD	28.700
T-0X	GG25	UNDOU	DVEOD	T-4X@V4	דדרים	0111	DK580	1-TVGA+	T 1 YAVA	1111/	C1117	DK580	N-C>	200		טאטטט	DK280
T-4X@V4	GG25	07000	DK280	T-0X	מטדד	C111	DK580	14 05	N-OX			DK580	TVC.O	T_1YBV8	17WG	0,000	DK580
T-4X@V8	G225	0000	DK580	N-OX				-	T-1x@V8	1111	F1117	UK580				CASI	
T-1X@V4	CZDD	CCSE	DK580	1-1Y614	7 1 1 1 1 1	6.011	UKSOU	28700	T-0X		F1117	עסטעע	_		_		DK580
RAPIXT-1	0000	にはって	DK580	1 - TVGA O	T 1VAVA	GJ11		חאבסט	1-4X@V8	1 40000	FI117	07000					DK580
1-4X@V4	T AVOVA	6,111	UK626	- 4%64	T_AYBVA	GGZ5	07000	NK 626	1-TYEA4	T 1VAVA	1111/	07010	DK 626	1-4X@V4	TAVOVA	GA21	DK626
1-TVEAC	T 1 VAVA	GJ11	UNOLO	20270	T-4X@V8	6 625	0000		1-4/640	T_//YAV/A	1111/	-117	DK626	1-4/640	T AVAVO	GA21	DK626
			ю						•								

FIG. 13-3

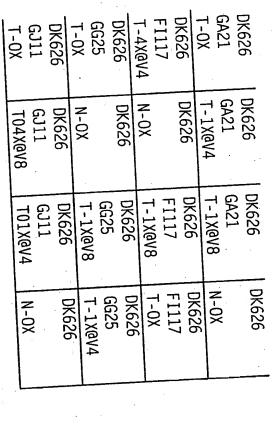


FIG. 13-4



